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**SSUSI Dayside  $F_2$ -Region Algorithm  
Language-Independent Description**

**Version 1.4**

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# SSUSI Dayside F<sub>2</sub>-Region Algorithm LID

## Table of Contents

<b>1. INTRODUCTION.....</b>	<b>1</b>
1.1 THE SSUSI DAYSIDE F <sub>2</sub> -REGION ALGORITHM .....	1
<b>1.1.1 Dayside Disk.....</b>	<b>1</b>
<b>1.1.2 Dayside Limb.....</b>	<b>2</b>
1.2 GOALS OF THE LANGUAGE-INDEPENDENT DESCRIPTION.....	2
1.3 CREDITS.....	3
<b>2. DERIVATION OF THE DAYSIDE F2-REGION DATA PRODUCTS.....</b>	<b>4</b>
2.1 GENERAL ALGORITHM EXPECTATIONS.....	4
2.2 DAYSIDE DISK.....	4
<b>2.2.1 The Ratio of O and N2 Vertical Column Densities (ROVCDN2VCD).....</b>	<b>4</b>
2.2.1.1 Required Input to the Derivation.....	4
2.2.1.2 Calculated Output of the Derivation .....	5
2.2.1.3 The Derivation .....	5
2.2.1.3.1 Begin .....	5
2.2.1.3.2 Calculate the ratio of O and N2 vertical column densities (ROVCDN2VCD).....	5
2.2.1.3.3 End .....	6
<b>2.2.2 The Solar EUV Flux Below 450 A (QEUV).....</b>	<b>6</b>
2.2.2.1 Required Input to the Derivation.....	6
2.2.2.2 Calculated Output of the Derivation .....	6
2.2.2.3 The Derivation .....	6
2.2.2.3.1 Begin .....	6
2.2.2.3.2 Calculate the solar EUV flux below 450 A (QEUV).....	6
2.2.2.3.3 End .....	7
<b>2.2.3 The F2-Region Peak Density (NmF2).....</b>	<b>7</b>
2.2.3.1 Required Input to the Derivation.....	7
2.2.3.2 Calculated Output of the Derivation .....	7
2.2.3.3 The Derivation .....	7
2.2.3.3.1 Begin .....	7
2.2.3.3.2 Calculate the F2-region peak density (NmF2) .....	7
2.2.3.3.3 End .....	8
<b>2.2.4 The Height of the F2-Region Peak Density (hmF2).....</b>	<b>8</b>
2.2.4.1 Required Input to the Derivation.....	8
2.2.4.2 Calculated Output of the Derivation .....	8
2.2.4.3 The Derivation .....	9
2.2.4.3.1 Begin .....	9
2.2.4.3.2 Calculate the height of the F2-region peak density (hmF2).....	9
2.2.4.3.3 End .....	9
<b>2.2.5 The F2-Region Total Electron Content (TEC).....</b>	<b>9</b>
2.2.5.1 Required Input to the Derivation.....	9
2.2.5.2 Calculated Output of the Derivation .....	10
2.2.5.3 The Derivation .....	10
2.2.5.3.1 Begin .....	10
2.2.5.3.2 Calculate the F2-region total electron content (TEC) .....	10
2.2.5.3.3 End .....	11
<b>2.2.6 The F2-Region Plasma Frequency (foF2).....</b>	<b>11</b>

2.2.6.1	Required Input to the Derivation .....	11
2.2.6.2	Calculated Output of the Derivation .....	11
2.2.6.3	The Derivation .....	11
2.2.6.3.1	Begin .....	11
2.2.6.3.2	Calculate the F2-region plasma frequency (foF2).....	11
2.2.6.3.3	End .....	11
2.3	DAYSIDE LIMB.....	11
<b>2.3.1</b>	<b>The Exospheric Temperature (Texo).....</b>	<b>11</b>
2.3.1.1	Required Input to the Derivation.....	11
2.3.1.2	Calculated Output of the Derivation .....	12
2.3.1.3	Internal data-items used by the Derivation. ....	12
2.3.1.4	The Derivation .....	12
2.3.1.4.1	Begin .....	12
2.3.1.4.2	Calculate the index corresponding to the element of ALTGRID which is closest to 500 km (INDEX_500KM).....	12
2.3.1.4.3	Calculate the index corresponding to the element of ALTGRID which is closest to 400 km (INDEX_400KM).....	12
2.3.1.4.4	Calculate the coefficients from a linear least squares fit to the natural logarithm of the values of the measured 1356 A intensity profile between 500 km and 400 km.(COEFF) 13	
2.3.1.4.5	Calculate the exospheric temperature (Texo).....	13
2.3.1.4.6	End .....	15
<b>2.3.2</b>	<b>The Neutral Density Profiles (N2DP, O2DP, ODP) .....</b>	<b>15</b>
2.3.2.1	Required Input to the Derivation.....	15
2.3.2.2	Calculated Output of the Derivation .....	15
2.3.2.3	The Derivation .....	16
2.3.2.3.1	Begin .....	16
2.3.2.3.2	Calculate the Neutral Density Profiles (NDP).....	16
2.3.2.3.3	End .....	16
<b>2.3.5</b>	<b>The Ratio of O and N2 Column Density ROVCDN2VCD.....</b>	<b>16</b>
2.3.5.1	Required Input to the Derivation.....	16
2.3.5.2	Calculated Output of the Derivation .....	16
2.3.5.3	Internal Data-Items Used by the Derivation .....	17
2.3.5.4	The Derivation .....	17
2.3.5.4.1	Begin .....	17
2.3.5.4.2	Calculate the N2 vertical column density profile (N2VCDP).....	17
2.3.5.4.3	Calculate the O vertical column density profile (OVCDP).....	18
2.3.5.4.4	Calculate the O vertical column density at N2VCDREF (OVCDREF).....	19
2.3.5.4.5	Calculate the ratio of O and N2 vertical column densities (ROVCDN2VCD).....	20
2.3.5.4.6	End .....	20
<b>2.3.6</b>	<b>The F2-Region Peak Density (NmF2).....</b>	<b>20</b>
2.3.6.1	Required Input to the Derivation.....	20
2.3.6.2	Calculated Output of the Derivation .....	21
2.3.6.3	The Derivation .....	21
2.3.6.3.1	Begin .....	21
2.3.6.3.2	Calculate the F2-region peak density (NmF2) .....	21
2.3.6.3.3	End .....	21
<b>2.3.7</b>	<b>The Height of the F2-Region Peak Density (hmF2).....</b>	<b>21</b>
2.3.7.1	Required Input to the Derivation.....	21
2.3.7.2	Calculated Output of the Derivation .....	22
2.3.7.3	The Derivation .....	22
2.3.7.3.1	Begin .....	22
2.3.7.3.2	Calculate the height of the F2-region peak density (hmF2).....	22
2.3.7.3.3	End .....	23
<b>2.3.8</b>	<b>The F2-Region Total Electron Content (TEC).....</b>	<b>23</b>
2.3.8.1	Required Input to the Derivation.....	23

2.3.8.2	Calculated Output of the Derivation.....	23
2.3.8.3	The Derivation.....	23
2.3.8.3.1	Begin.....	23
2.3.8.3.2	Calculate the F2-region total electron content (TEC).....	23
2.3.8.3.3	End.....	24
<b>2.3.9</b>	<b>The F2-Region Plasma Frequency (foF2).....</b>	<b>24</b>
2.3.9.1	Required Input to the Derivation.....	24
2.3.9.2	Calculated Output of the Derivation.....	24
2.3.9.3	The Derivation.....	24
2.3.9.3.1	Begin.....	24
2.3.9.3.2	Calculate the F2-region plasma frequency (foF2).....	24
2.3.9.3.3	End.....	24
<b>3.</b>	<b>APPENDIX.....</b>	<b>25</b>
3.1	THE ROVCDN2VCD DATA TABLE FUNCTION (ROVCDN2VCD DTF).....	25
3.1.1	<i>Required Input to the Derivation.</i> .....	25
3.1.2	<i>Calculated Output of the Derivation.</i> .....	25
3.1.3	<i>Contents of the ROVCDN2VCD Data Table:</i> .....	25
3.1.4	<i>The Derivation</i> .....	27
3.1.4.1	Begin.....	27
3.1.4.2	Interpolate on DTRI1356ILBH2 to obtain a one-dimensional vector of DTRI1356ILBH2 values as a function of DTROVCDN2VCD at input SZA value (INTRPDTRI1356ILBH2). .....	27
3.1.4.3	Interpolate on PDDTROVCDN2VCD to obtain the value of PDDTROVCDN2VCD which corresponds to the input RI1356ILBH2 and SZA values (INTRPPDDTROVCDN2VCD). .....	28
3.1.4.4	Interpolate on DTVRI1356ILBH2 to obtain the value of DTVRI1356ILBH2 which corresponds to the input RI1356ILBH2 value (INTRPDTVRI1356ILBH2).....	28
3.1.4.5	Interpolate on the vector DTROVCDN2VCD to obtain the value of DTROVCDN2VCD which corresponds to the input RI1356ILBH2 value (ROVCDN2VCD). .....	29
3.1.4.6	End.....	29
3.2	THE QEUV DATA TABLE FUNCTION (QEUV DTF).....	29
3.2.1	<i>Required Input to the Derivation.</i> .....	29
3.2.2	<i>Calculated Output of the Derivation.</i> .....	30
3.2.3	<i>Contents of the QEUV Data Table:</i> .....	30
3.2.4	<i>The Derivation</i> .....	32
3.2.4.1	Begin.....	32
3.2.4.2	Interpolate on DTI1356 to obtain the value of DTI1356 which corresponds to the input ROVCDN2VCD and SZA values (INTRPDTI1356).....	32
3.2.4.3	Interpolate on DTVI1356 to obtain the value of DTVI1356 which corresponds to the input ROVCDN2VCD and SZA values (INTRPDTVI1356).....	32
3.2.4.4	Interpolate on PDDTI1356 to obtain the value of PDDTI1356 which corresponds to the input ROVCDN2VCD and SZA values (INTRPPDDTI1356). .....	33
3.2.4.5	Calculate the solar EUV flux below 450 A (QEUV). .....	34
3.2.4.6	End.....	35
3.3	THE EDPP DATA TABLE FUNCTION (EDPP DTF).....	35
3.3.1	<i>Required Input to the Derivation.</i> .....	35
3.3.2	<i>Calculated Output of the Derivation.</i> .....	35
3.3.3	<i>Contents of the EDPP Data Table:</i> .....	35
3.3.4	<i>The Derivation</i> .....	46
3.3.4.1	Begin.....	46
3.3.4.2	Calculate the index corresponding to the element of the vector DTROVCDN2VCD which is closest to the input value ROVCDN2VCD (INDEXDTROVCDN2VCD). .....	46
3.3.4.3	Calculate the index corresponding to the element of the vector DTQEUV which is closest to the input value QEUV (INDEXDTQEUV). .....	46

3.3.4.4	Calculate the index corresponding to the element of the vector DTSEASON which is closest to the input value MONTH (INDEXDTSEASON).....	47
3.3.4.5	Calculate the index corresponding to the element of the vector DTGMLT which is closest to the input value GMLT (INDEXDTGMLT).....	47
3.3.4.6	Calculate the index corresponding to the element of the vector DTGMLAT which is closest to the input value GMLAT (INDEXDTGMLAT).....	47
3.3.4.7	Calculate the index corresponding to the element of the vector DTGMLON which is closest to the input value GMLON (INDEXDTGMLON).....	47
3.3.4.8	Calculate the F2-region peak density (NmF2).....	48
3.3.4.9	Calculate the height of the F2-region peak density (hmF2).....	49
3.3.4.10	Calculate the F2-region total electron content (TEC).....	50
3.3.4.11	End.....	51
3.4	THE DISCRETE INVERSE THEORY DATA TABLE FUNCTION (DITDTF).....	51
3.4.1	<b>Required Input to the Derivation.</b> .....	<b>51</b>
3.4.2	<b>Calculated Output of the Derivation.</b> .....	<b>51</b>
3.4.3	<b>Contents of the Discrete Inverse Theory Data Table:</b> .....	<b>52</b>
3.4.4	<b>The Derivation</b> .....	<b>57</b>
3.4.4.1	Begin.....	57
3.4.4.2	Calculate the index corresponding to the element of the vector DTTexo which is closest to the input value Texo (INDEXDTTexo).....	57
3.4.4.3	Calculate the index corresponding to the element of the vector DTSCLN2 which is closest to the input value SCLN2 (INDEXDTSCLN2).....	57
3.4.4.4	Calculate the index corresponding to the element of the vector DTSCLO2 which is closest to the input value SCLO2 (INDEXDTSCLO2).....	57
3.4.4.5	Calculate the index corresponding to the element of the vector DTSCLO which is closest to the input value SCLO (INDEXDTSCLO).....	57
3.4.4.6	Calculate the model 1356 A intensity profile (I1356P).....	58
3.4.4.7	Calculate the model LBH1 (1400-1500 A) intensity profiles (ILBH1P).....	60
3.4.4.8	Calculate the model LBH2 (1650-1800 A) intensity profiles (ILBH2P).....	62
3.4.4.9	Calculate the model data intensity profile (MDIP).....	63
3.4.4.10	Calculate the model N2 density profile (N2DP).....	64
3.4.4.11	Calculate the model O2 density profile (O2DP).....	67
3.4.4.12	Calculate the model O density profile (ODP).....	69
3.4.4.13	End.....	72
3.5	THE DISCRETE INVERSE THEORY FUNCTION (DITF).....	72
3.5.1	<b>Required Input to the Derivation.</b> .....	<b>72</b>
3.5.2	<b>Calculated Output of the Derivation.</b> .....	<b>72</b>
3.5.3	<b>The Derivation</b> .....	<b>73</b>
3.5.3.1	Begin.....	73
3.5.3.2	Calculate the index of ALTGRID which is 50 km below the expected tangent altitude of the measured intensity profile peaks (INDEXBELOW).....	73
3.5.3.3	Calculate the index of ALTGRID which is 50 km above the expected tangent altitude of the measured intensity profile peaks (INDEXABOVE).....	73
3.5.3.4	Setup the measured data vector (d).....	74
3.5.3.5	Setup the measured data variance vector (Vd).....	74
3.5.3.6	Calculate the neutral density scale factor values (SCLN2, SCLO2, SCLO).....	76
3.5.3.6.1	Determine the indices of the one-dimensional vectors DTSCLN2, DTSCLO2, and DTSCLO of the DIT Data Table Function which correspond to the model data which best fits the measured data (INDEXSCLN2, INDEXSCLO2, INDEXSCLO).....	76
3.5.3.6.2	Determine the best estimate of the neutral density scale factors by fitting a parabola through the minimum of each dimension of the three-dimensional vector CHISQ (SCLN2, SCLO2, SCLO).....	77
3.5.3.7	Calculate the variance associated with the neutral density scale factors (VSCLN2, VSCLO2, VSCLO).....	79

3.5.3.7.1	Setup the model data corresponding to INDEXSCLN2, INDEXSCLO2, and INDEXSCLO (G).....	79
3.5.3.7.2	Setup the model data gradient matrix (GRADG).....	79
3.5.3.7.3	Setup the measured data covariance matrix (CVd).....	82
3.5.3.7.4	Setup the model data covariance matrix (CVG).....	83
3.5.3.7.5	Calculate the sum of the data covariance matrix and the model covariance matrix (CVdPCVG).....	84
3.5.3.7.6	Calculate the inverse of the sum of the data covariance matrix and the model covariance matrix (CVdPCVGINV).....	84
3.5.3.7.7	Calculate the transpose of the model data gradient matrix (GRADGT).....	84
3.5.3.7.8	Calculate the generalized inverse of the model gradient matrix (GRADGINV).....	84
3.5.3.7.9	Calculate the transpose of the model gradient generalized inverse matrix (GRADGINVT).....	85
3.5.3.7.10	Calculate the variances associated with the neutral density scale factors (VSCLN2, VSCLO2, VSCLO).....	85
3.5.3.8	Calculate the N2 density profile (N2DP).....	86
3.5.3.9	Calculate the O2 density profile (O2DP).....	86
3.5.3.10	Calculate the O density profile (ODP).....	87
3.5.3.11	End.....	88
3.6	THE DERIVATIVE FUNCTION (DERIVATIVE).....	88
3.6.1	<b>Required Input to the Derivation</b> .....	88
3.6.2	<b>Calculated Output of the Derivation</b> .....	88
3.6.3	<b>The Derivation</b> .....	88
3.6.3.1	Begin.....	88
3.6.3.2	Calculate the derivative of the vector Y at the abscissa value X [INDEX] (RESULT).....	88
3.6.3.3	End.....	89
3.7	THE INTERPOLATE FUNCTION (INTERPOLATE).....	89
3.7.1	<b>Required Input to the Derivation</b> .....	89
3.7.2	<b>Calculated Output of the Derivation</b> .....	89
3.7.3	<b>The Derivation</b> .....	89
3.7.3.1	Begin.....	89
3.7.3.2	Calculate the index corresponding to the element of the vector X which is closest to the input abscissa value U (INDEX).....	89
3.7.3.3	Calculate the index corresponding to the element of the vector TempX which is closest to the input abscissa value U (INDEX).....	90
3.7.3.4	Interpolate the vector TempY at the abscissa value U (RESULT).....	90
3.7.3.5	End.....	91
3.8	THE SEARCH FUNCTION (SEARCH).....	91
3.8.1	<b>Required Input to the Derivation</b> .....	91
3.8.2	<b>Calculated Output of the Derivation</b> .....	91
3.8.3	<b>The Derivation</b> .....	91
3.8.3.1	Begin.....	91
3.8.3.2	Initialize temporary indices (IL and IU).....	91
3.8.3.3	Repeat the following calculations until IU - IL = 1.....	92
3.8.3.4	Determine whether index IL or IU of the vector X has a corresponding value which is closest to the value U.....	92
3.8.3.5	End.....	92
3.9	THE LINEAR LEAST SQUARES FITTING FUNCTION (LLSFIT).....	92
3.9.1	<b>Required Input to the Derivation</b> .....	92
3.9.2	<b>Calculated Output of the Derivation</b> .....	93
3.9.3	<b>The Derivation</b> .....	93
3.9.3.1	Begin.....	93
3.9.3.2	Calculate the coefficients of the linear least squares fit of the function Y (RESULT).....	93
3.9.3.3	End.....	94
3.10	THE MATRIX ADDITION FUNCTION (ADD).....	94

<b>3.10.1 Required Input to the Derivation</b> .....	94
<b>3.10.2 Calculated Output of the Derivation</b> .....	95
<b>3.10.3 The Derivation</b> .....	95
3.10.3.1 Begin.....	95
3.10.3.2 Calculate the addition of matrix A and matrix B (RESULT).....	95
3.10.3.3 End.....	95
3.11 THE MATRIX SUBTRACTION FUNCTION (SUBTRACT).....	95
<b>3.11.1 Required Input to the Derivation</b> .....	95
<b>3.11.2 Calculated Output of the Derivation</b> .....	95
<b>3.11.3 The Derivation</b> .....	95
3.11.3.1 Begin.....	95
3.11.3.2 Calculate the subtraction of matrix B from matrix A (SUBTRACT).....	95
3.11.3.3 End.....	96
3.12 THE MATRIX MULTIPLICATION FUNCTION (MULTIPLY).....	96
<b>3.12.1 Required Input to the Derivation</b> .....	96
<b>3.12.2 Calculated Output of the Derivation</b> .....	96
<b>3.12.3 The Derivation</b> .....	96
3.12.3.1 Begin.....	96
3.12.3.2 Calculate the product of matrix A and matrix B (MULTIPLY).....	96
3.12.3.3 End.....	97
3.13 THE MATRIX TRANSPOSE FUNCTION (TRANSPOSE).....	97
<b>3.13.1 Required Input to the Derivation</b> .....	97
<b>3.13.2 Calculated Output of the Derivation</b> .....	97
<b>3.13.3 The Derivation</b> .....	97
3.13.3.1 Begin.....	97
3.13.3.2 Calculate the transpose of matrix A (RESULT).....	97
3.13.3.3 End.....	97
3.14 THE IDENTITY MATRIX FUNCTION (IDENTITY).....	97
<b>3.14.1 Required Input to the Derivation</b> .....	97
<b>3.14.2 Calculated Output of the Derivation</b> .....	97
<b>3.14.3 The Derivation</b> .....	98
3.14.3.1 Begin.....	98
3.14.3.2 Construct an NxN identity matrix (RESULT).....	98
3.14.3.3 End.....	98
3.15 THE MATRIX SOLVE FUNCTION (SOLVE).....	98
<b>3.15.1 Required Input to the Derivation</b> .....	98
<b>3.15.2 Calculated Output of the Derivation</b> .....	98
<b>3.15.3 The Derivation</b> .....	98
3.15.3.1 Begin.....	98
3.15.3.2 Calculate the implicit scaling vector (ISV).....	98
3.15.3.3 Initialize the diagonal elements of the lower-upper decomposition matrix (LUDCMP).....	99
3.15.3.4 Repeat the following calculations for each column of matrix A.....	99
3.15.3.4.1 Calculate the upper triangular elements of matrix LUDCMP.....	99
3.15.3.4.2 Calculate the lower triangular elements of matrix LUDCMP.....	100
3.15.3.4.3 Calculate the pivot index for the jth column of matrix A (PINDEX).....	100
3.15.3.4.4 If PINDEX[j] is not equal to the value of j (the jth column of matrix A) then interchange the rows of LUDCMP in the jth column.....	101
3.15.3.4.5 If PINDEX[j] is not equal to the value of j (the jth column of matrix LUDCMP) then interchange the implicit scaling values for row j and the pivot row.....	101
3.15.3.4.6 If $j \neq N$ then divide matrix LUDCMP by the pivot element.....	101
3.15.3.5 Repeat the following calculations for each column of matrix B.....	102
3.15.3.5.1 Initialize the forward substitution vector Y to hold the elements of the jth column of matrix B (Y).....	102
3.15.3.5.2 Calculate the vector Y by forward substitution (Y).....	102

3.15.3.5.3 Calculate the $j$ th column of the matrix RESULT by backward substitution (RESULT). .....	102
3.15.3.5 End .....	103
3.16 REFERENCES .....	103
3.17 MODIFICATION HISTORY .....	104



# 1. Introduction

This document provides a language-independent description (LID) of the SSUSI Dayside F<sub>2</sub>-Region algorithm. The purpose of the LID is to provide a detailed outline of the steps required to calculate the Dayside environmental data products and their associated uncertainties using any programming language. Section 1 provides a brief discussion of the required inputs and the essential outputs of the dayside disk and dayside limb algorithms. Section 2 gives a detailed description of the steps required to derive dayside disk and limb data products and their corresponding uncertainties. Finally, in Section 3, we provide a detailed description of the data table algorithms, the Discrete Inverse Theory Function, and any supporting functions required by the SSUSI Dayside F<sub>2</sub>-Region Algorithm.

## 1.1 The SSUSI Dayside F<sub>2</sub>-Region Algorithm

The SSUSI Dayside F<sub>2</sub>-Region algorithm accepts specific Ultra-Violet intensities on a pixel-by-pixel basis, and generates the output products listed below for each pixel. A pixel which represents a measurement made while viewing the Earth's hard disk is referred to as a disk pixel. A pixel which represents a measurement made while viewing the Earth's limb actually includes a complete set of measurements made when viewing from the largest tangent altitude down to the Earth's hard disk.. The output products for an individual pixel do not represent the entire dayside portion of the observing region. However, when the output products for all pixels in the dayside are superimposed over a model of the Earth, the dayside region is well described.

The Dayside F<sub>2</sub>-Region Algorithm is divided into disk and limb subsections in the derivations provided in Section 2 below. Our intent is to clearly identify the steps required to calculate data products for both disk and limb pixels. Although some derivations are similar, disk and limb pixels should be treated as entirely separate entities.

### 1.1.1 Dayside Disk

The dayside disk algorithm processes sensor data which are calibrated, geolocated, and rectified. The disk algorithm utilizes look-up tables generated from first principles science codes to rapidly calculate dayside disk F<sub>2</sub>-Region data products from disk measurements of daytime atomic and molecular UV emissions. The data products derived by the day disk algorithm are

- |                |  |
|----------------|--|
| (1) QEUV       | Solar EUV flux (erg cm <sup>-2</sup> s <sup>-1</sup> )   |
| (2) ROVCDN2VCD | Ratio of O and N <sub>2</sub> vertical column densities (dimensionless).                         |
| (3) NmF2       | F <sub>2</sub> -Region Peak Density (cm <sup>-3</sup> )  |
| (4) hmF2       | F <sub>2</sub> -Region Height of the Peak Density (km)   |
| (5) TEC        | F <sub>2</sub> -Region Total Electron Content (10 <sup>16</sup> e <sup>-</sup> m <sup>-2</sup> ) |
| (6) foF2       | F <sub>2</sub> -Region Plasma Frequency (s <sup>-1</sup> ).                                      |

### 1.1.2 Dayside Limb

The dayside limb algorithm processes SIS scan data for the limb portion of the SDR grid. The limb algorithm utilizes some look-up tables in combination with an inversion algorithm to calculate dayside limb F<sub>2</sub>-Region data products. The derived data products are

(1) N2	Density profile of molecular nitrogen (cm <sup>-3</sup> ).
(2) O2	Density profile of molecular oxygen (cm <sup>-3</sup> ).
(3) O	Density profile of atomic oxygen (cm <sup>-3</sup> ).
(4) Texo	Temperature of the exobase (K).
(5) ROVCDN2VCD	Ratio of O and N <sub>2</sub> vertical column densities (dimensionless).
(6) NmF2	F <sub>2</sub> -Region Peak Density (cm <sup>-3</sup> )
(7) hmF2	F <sub>2</sub> -Region Height of the Peak Density (km)
(8) TEC	F <sub>2</sub> -Region Total Electron Content (10 <sup>16</sup> e <sup>-</sup> m <sup>-2</sup> )
(9) foF2	F <sub>2</sub> -Region Plasma Frequency (s <sup>-1</sup> ).

### 1.2 Goals of the Language-Independent Description

The driving force behind the Language-Independent Description (LID) is the desire to preserve the intellectual knowledge which lies at the foundation of most scientific software. A LID attempts to form an agreement (or “contract” if you will) between the theorist and the implementor. The role of the theorist in creating the LID is to specify the algorithm completely, leaving no room for interpretation on the part of the implementor. The role of the implementor is to take the LID and develop it into an operational system, meeting the requirements of the particular system with respect to design methodology, maintainability, speed, and so on.

Modern programming languages do not serve as an optimal medium for LID expression. Programming languages often impose a syntax which constrains the expressive ability of the LID author. In addition, programming languages can be complex and can possess hidden subtleties. The syntax alone can place a double-requirement upon the author, because the author is forced to become both a theorist and a programmer. In the modern world, where computer programming languages and computer architectures are in a state of constant evolution, tying the expression of knowledge to a programming language can be a costly and error-prone mistake.

To summarize then, the SSUSI Dayside F<sub>2</sub>-Region Algorithm Language-Independent Description attempts to:

- Clearly, and without interpretation, express the derivations of the Dayside F<sub>2</sub>-Region Algorithm data products.
- Provide an easily understood sequence of calculations which are broken down into “atomic” steps.

- Immortalize the algorithm by transcending any particular programming language or computer architecture, thereby preserving the knowledge and portability.
- Provide a basis for testing, in that test cases can be based upon the LID, and expected results can be computed by an external method (verification from an external source).
- Enhance requirements traceability. Since each step in the LID is “atomic” and labeled, the implementor can easily document where and how each step is accomplished. This forms a cross-reference between the code and the LID.
- Enhance maintainability. Due to the labeling of the steps in the LID, a maintainer of the code should be able to easily identify where changes should be made, and where they should not.
- Leave sufficient room for creativity on the part of the implementor, so that coding the algorithm in a programming language does not become a robotic process.

### 1.3 Credits

Although this document stands alone as the Language-Independent Description of the SSUSI Dayside  $F_2$ -Region Algorithm, its format and design are intended to be consistent with the SSUSI Auroral E-Region Algorithm LID and the SSUSI Nightside  $F_2$ -Region Algorithm LID prepared by the Johns Hopkins University Applied Physics Laboratory.